# Geodesic spaces : momentum 

$$
\begin{gathered}
:: \\
\text { Groups : symmetry }
\end{gathered}
$$

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## 1. Reprise of the relevant bits of my BLAST '08/9 talks

Goal: express each of the five postulates of Book I of Euclid's Elements equationally.
Their bilinear content is confined to the 3rd and 4th postulates, concerning respectively circles and right angles.
Bilinearity is equational. $\checkmark$
But those equations depend on numbers, which Book I outlawed.
The obvious trick of identifying the Euclidean line with the underlying field would appear to inevitably lose information in a way that prevents the square of the line from being a Euclidean space.
Absent bilinearity we have only affine spaces.
Question: Can each of postulates 1,2 , and 5 be written equationally, observing the proscription on numbers, so that together they define a variety of affine spaces over some field $k$ ?
Answer: Yes, for $k$ each of $\mathbb{Q}$ and $\mathbb{Q}[\mathbf{i}]$ (complex rationals)

## 2. Approach

1. We defined a variety Grv of "groves" with a binary operation $a b$ denoting the point to which segment $A B$ must be produced to double its length, interpretable in $\mathbf{A b}$ as $a b=2 b-a$. Writing $a b c$ for $(a b) c$, we expressed Postulate 2 as $a a=a b b=a$, while Postulate 5 became $a b(c d)=a c(b d)$.
2. We equipped Grv with $\omega$ many commutative but non-associative $n$-ary centroid operations $a_{1} \oplus a_{2} \oplus \ldots \oplus a_{n}$.
We wrote Postulate 1 as two equations

$$
\begin{array}{r}
a_{1} \oplus \ldots \oplus a_{n-1} \oplus\left(\left(a_{1} \oplus \ldots \oplus a_{n-1}\right) \xrightarrow{n} b\right) \quad=b \\
\left(a_{1} \oplus \ldots \oplus a_{n-1}\right) \xrightarrow{n}\left(a_{1} \oplus \ldots \oplus a_{n}\right)=a_{n},
\end{array}
$$

for each centroid operation in terms of $a b(a \stackrel{4}{\rightarrow} b=a b a b$ etc.) We showed that the resulting variety is equivalent to $\mathbf{A f f} \mathbb{Q}_{\mathbb{Q}}$.
3. We extended $\mathbb{Q}$ to $\mathbb{Q}[i]$ with a binary operation $a \cdot b$ denoting $b$ rotated 90 degrees about $a$.
End of reprise.

## 3. This talk; Geodesic spaces

At FMCS (Vancouver May 2009) Pieter Hofstra asked:
Can non-Euclidean geometry be treated analogously?
My answer (weeks later): weaken Postulate 5 to right distributivity,

$$
a b c=a c(b c)
$$

Thinking of $b a, a, b, a b$, etc. as points evenly spaced along a geodesic $\gamma$, right distributivity expresses a symmetry of $\gamma$ about an arbitrary point $c$, namely that the inversion $\gamma c$ in $c=$
$\ldots, b a c, a c, b c, a b c, \ldots$ is itself a geodesic, namely
$\ldots, b c(a c), a c, b c, a c(b c), \ldots$
These algebras have sometimes been identified with quandles as used to algebraicize knot theory. This is wrong because the quandle operations interpreted in Grp are $b^{-1} a b$ and $b a b^{-1}$, which collapse in $\mathbf{A} \mathbf{b}$ to $a b=a$, whereas the above is $b a^{-1} b$ which is very useful in $\mathbf{A b}$.

## 4. Geodesic theory

A geodesic space or geode is an algebraic structure with a binary operation $x \rightarrow y$, or $x y$, of extension (with $x y z$ for $(x y) z$ ) satisfying
G0 $x x=x$
G1 $x y y=x$
G2 $x y z=x z(y z)$

Geometrically, segment $A_{0} A_{1}$ is extended to $A_{2}=A_{0} \rightarrow A_{1}$ by producing $A_{0} A_{1}$ to twice its length: $\left|A_{0} A_{2}\right|=2\left|A_{0} A_{1}\right|$.


## Examples

Symmetric spaces: Affine, hyperbolic, elliptic, etc.
Groups: Interpret $x \rightarrow y$ as $y x^{-1} y$ (abelian groups: $2 y-x$ )
Number systems: Integers, rationals, reals, complex numbers, etc.
Combinatorial structures: sets, dice, etc.

## 5. Geodesics

A discrete geodesic $\gamma\left(A_{0}, A_{1}\right)$ is a subspace generated by $A_{0}, A_{1}$.
A geodesic in $S$ is a directed union of discrete geodesics in $S$.
Examples: $\mathbb{Z}, \mathbb{Z}_{n}, \mathbb{Q}, \mathbb{Q} / \mathbb{Z}, \mathbb{E}(\S 11)$. Not $\mathbb{R}$ (not fully represented).
Geodesics properly generalize cyclic groups.
Example: $\mathbb{E}=\mathbb{Z}_{4} /\{0=2\} . \quad 2=0 \quad 3$
$S$ is torsion-free when every finite geodesic in $S$ is a point.
The connected components of $\gamma\left(A_{0}, A_{1}\right)$ are $\ldots, A_{-2}, A_{0}, A_{2}, \ldots$ and $\ldots A_{-1}, A_{1}, A_{3}, \ldots$. These become one component just when $A_{0}=A_{2 n+1}$ for some $n$, as with $\mathbb{Z}_{3}, \mathbb{Z}_{5}$, etc.

## The category Gsp

Geode homomorphism: a map $h: S \rightarrow T$ s.t. $h(x y)=h(x) h(y)$.
Denote by Gsp the category of geodes and their homomorphisms.

## 6. Sets

Theorem 1. For any space $S$, the following are equivalent.
(i) $\gamma(A, B)=\{A, B\}$ for all $A, B \in S$ (cf. $\gamma(N, S)$, N\&S poles).
(ii) The connected components of $S$ are its points.
(iii) $x y=x$ for all $x, y \in S$.

A set is a geode $S$ with any (hence all) of those properties.
Define $U_{\text {SetGsp }}:$ Set $\rightarrow \mathbf{G s p}$ as $U_{\text {SetGsp }}(X)=\left(X, \pi_{1}^{2}\right)$, i.e. $x y \stackrel{\text { def }}{=} x$. Left adjoint $F_{\text {GspSet }}(S)=$ the set of connected components of $S$.
Cf. $\mathcal{D}:$ Set $\rightarrow$ Top where $\mathcal{D}(X)=\left(X, 2^{X}\right)$, a discrete space.
These embed Set fully in Top (Pos, Grph, Cat, etc.) and Gsp.
In Top etc. the embedding $\mathcal{D}$ preserves colimits.
In Gsp the (reflective) embedding $U_{\text {SetGsp }}$ preserves limits!
In Set, $1+1=2$ and $2^{\aleph_{0}}=\beth_{1}$ (discrete continuum).
In Top, $1+1=2$ but $2^{\aleph_{0}}=$ Cantor space, not discrete.
In Gsp, $2^{\aleph_{0}}=\beth_{1}$, discrete (!), but $1+1=\mathbb{Z}$, a homogeneous (no origin) geodesic with two connected components.

## 7. Normal form terms and free spaces

A normal form geodesic algebra term over a set $X$ of variables is one with no parentheses or stuttering, namely a finite nonempty word $x_{1} x_{2} \ldots x_{n}$ over alphabet $X$ with no consecutive repetitions.

Theorem 2. All terms are reducible to normal form using G0-G2. ( G 2 removes parentheses while G 1 and G 0 remove repetitions.)
Theorem 3. The normal form terms over $X$ form a geode.
Denote this space by $F(X)$, the free space on $X$ consisting of the " $X$-ary" operations. $F(\})=\mathbf{0}$ (initial), $F(\{0\})=\mathbf{1}$ (final).
$F(\{0,1\})=1+1$ has two connected components $0 \alpha$ and $1 \alpha$. It is an infinite discrete geodesic $\gamma(0,1)=\{0 \xrightarrow{n} 1\}=$

$$
\mathbb{Z}=\ldots, 1010,010,10,0,1,01,101,0101, \ldots
$$

Call this geodesimal notation, tally notation with sign and parity bits. Geodesimal operations: $x \xrightarrow{3} y=y x y, x \xrightarrow{-3} y=y x y x$, etc.
8. The free space $1+1+1$. 3 connected components $0 \alpha, 1 \alpha, 2 \alpha$


All points out to $\infty$ shown. Curvature $\kappa$ undefined $(-\infty)$.
Triangles congruent by defn. but $\angle, \angle$, and $\angle$ incomparable.
$\exists$ disjoint inclined geodesics: $\gamma(101,201) \cap \gamma(102,202)=\emptyset($ barely! $)$

## 9. The curvature hierarchy



All spaces (including $1+1+1$ itself) homogeneous.
Not shown: Sets $(x y=x, \S 3)$, Dice $(x y x y=x, \S 11)$.

## 10. Dice and subdirect irreducibles of Grv

The edge $\mathbb{E}=\mathbb{E}_{3}=\{1,0=2,3\}$ is the unique geodesic with an odd number of points and two connected components.

- $\mathbb{E}_{3}=\mathbb{Z}_{4} /\{0=2\}$
- $\mathbb{E}_{6}=\mathbb{Z}_{8} /\{0=4,2=6\}$
- $\mathbb{E}_{12}=\mathbb{Z}_{16} /\{0=8,2=10,4=12,6=14\}$, etc.
$\mathbf{A b}$ and Grv have the same SI's (subdirect irreducibles), namely $\mathbb{Z}_{p^{n}}$, $n \leq \infty$, as groves, except for $p=2$ when $\mathbb{Z}_{4.2^{n}}$ is replaced by $\mathbb{E}_{3.2^{n}}$ in Grv. $\left(\mathbb{Z}_{p \infty}\right.$ is the Prüfer $p$-group $=$ the direct limit of the inclusion $\mathbb{Z}_{p^{0}} \subseteq \mathbb{Z}_{p^{1}} \subseteq \mathbb{Z}_{p^{2}} \subseteq \ldots$. ) Key fact: $\mathbb{Z}_{4}$ is a subdirect product of $\mathbb{E}$ 's.
$\mathbb{E} \in \mathcal{V}$ iff $\mathbb{Z}_{4} \in \mathcal{V}$ for all varieties $\mathcal{V} \subseteq \mathbf{G s p}$.
A die is a subspace of $\mathbb{E}^{n}, n \leq \infty$. Equivalently, a model of $x x=x y y=x, x y x y=x$.
Dice $=H S P\left(\mathbb{Z}_{4}\right)=S P(\mathbb{E}) \subset$ Grv.


## 11. The geodesic neighborhood

Operations: xy [yxy] [yxz] $x y, x^{-1}, e$


Set $\stackrel{x\left(\pi_{2}^{3}\right)}{{ }^{2}}$ Cube $\stackrel{y+x+z}{ }$ Cube $_{*}{ }^{x+y}$ Bool

Every path in this commutative diagram denotes a forgetful functor, hence one with a left adjoint. Vertical arrows forget the indicated equation, horizontal arrows interpret the blue operation above as the arrow's label. E.g. the left adjoint of the functor $U_{\text {AbGrp }}: \mathbf{A b} \rightarrow \mathbf{G r p}$ is abelianization, the arrow to Schar from $\mathbf{A b}$ interprets Schar's [yxz] as $y-x+z$ in $\mathbf{A b}$, the left adjoint of the functor $U_{\text {SetGsp }}:$ Set $\rightarrow$ Gsp gives the set $F_{\text {GspSet }}(S)$ of connected components of $S$, and so on.

## 12. Groves: Grv $=$ Gsp + G3. Euclid's 5th postulate



Euclid's fifth or parallel postulate: $E X$ and $H Y$, when inclined inwards, meet when produced. Euclid: "inclined" $=\alpha+\beta<180^{\circ}$.

Our inclination condition: a witness triangle $\triangle A E H$ with parallelogram BCGF (centroid D) s.t $B, C$ at midpoints of $A E, A H$.

Our 5th postulate: $E F$ and $H G$, when obtained by extending the four sides of the skew quadrilateral $A B D C$, meet when extended.

$$
\begin{align*}
A \rightarrow B & \rightarrow(C \rightarrow D)  \tag{G3}\\
E & \rightarrow F \rightarrow C \rightarrow(B \rightarrow D) \\
E & =H
\end{align*} \rightarrow G
$$

G3

$$
x y(z w)=x z(y w)|x y w z=x z w y| x y w z y w z=x \mid x 102102=x
$$

