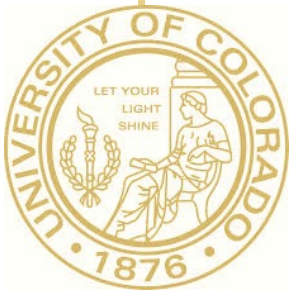


Optimization and Control of Networks

# S-modular Games and Power Control

Lijun Chen

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# Agenda

- ❑ S-modular games
  - ❑ Supermodular games
  - ❑ Submodular games
- ❑ Power control
  - ❑ Power control via pricing
  - ❑ A general framework for distributed power control

# Supermodular games

- ❑ Characterized by “strategic complementarities”
- ❑ Supermodular games are remarkable
  - ❑ Pure strategy Nash equilibrium exists
  - ❑ The equilibrium set has an order structure with extreme elements
  - ❑ Many solution concepts yield the same prediction
  - ❑ Analytically appealing
    - Have nice comparative statics and behave well under various learning or adaptive algorithms
  - ❑ Encompass many applied models

# Monotone comparative statics

- Def: suppose  $X \subseteq R$  and  $T$  some partially ordered set. A function  $f : X \times T \rightarrow R$  has **increasing differences** (supermodular) in  $(x, t)$  if for all  $x' \geq x$  and  $t' \geq t$ ,

$$f(x', t') - f(x, t') \geq f(x', t) - f(x, t).$$

- The incremental gain to choose a higher  $x$  is greater when  $t$  is higher.
- The increasing differences is symmetric, i.e., if  $t' \geq t$ , then  $f(x, t') - f(x, t)$  is nondecreasing in  $x$ .

□ Lemma: if  $f$  is twice continuously differentiable, then  $f$  has increasing differences iff  $t' \geq t$  implies

$$f_x(x, t') \geq f_x(x, t)$$

for all  $x$ , or alternatively that, for all  $x, t$ ,

$$f_{xt}(x, t) \geq 0$$

- A central question: when  $x(t) = \arg \max_{x \in X} f(x, t)$  will be increasing in  $t$  ?
- Theorem (Topkis): Let  $X \subseteq R$  be compact and  $T$  a partially ordered set. Suppose  $f : X \times T \rightarrow R$  has increasing differences in  $(x, t)$ , and is upper semi-continuous in  $x$ . Then,
  - For all  $t$ ,  $x(t)$  exists and has a greatest and least element  $\bar{x}(t)$  and  $\underline{x}(t)$ .
  - $\bar{x}(t)$  and  $\underline{x}(t)$  are increasing in  $t$ .

## □ Proof:

- Existence:  $X$  is compact and  $f$  is upper semicontinuous
- Take a sequence  $\{x^k\}$  in  $x(t)$ . From compactness, there exists a limit point  $\bar{x} = \lim_{k \rightarrow \infty} x^k$ . Then for all  $x$ ,

$$f(x^k, t) \geq f(x, t) \Rightarrow f(\bar{x}, t) \geq f(x, t).$$

Thus,  $\bar{x} \in x(t)$  and  $x(t)$  is therefore closed. It follows that  $x(t)$  has a greatest and least element.

- Let  $x \in x(t)$  and  $x' \in x(t')$ . Then,  $f(x, t) - f(\min(x, x'), t) \geq 0$ , which implies  $f(\max(x, x'), t) - f(x', t) \geq 0$ . By the increasing difference,  $f(\max(x, x'), t') - f(x', t') \geq 0$ . Thus  $\max(x, x')$  maximizes  $f(\cdot, t')$ . Now, pick  $x = \bar{x}(t)$  and  $x' = \bar{x}(t')$ , it follows that  $x' \geq x$ . A similar argument applies to  $\underline{x}(t)$ .

# Supermodular games

- Def: the game  $G = \{N, S_{i \in N}, u_{i \in N}\}$  is a supermodular game if for all  $i$ ,
  - $S_i$  is a compact subset of  $R$
  - $u_i$  is upper semicontinuous in  $s_i, s_{-i}$
  - $u_i$  has increasing differences in  $(s_i, s_{-i})$
- Corollary: suppose  $G = \{N, S_{i \in N}, u_{i \in N}\}$  is a supermodular game. Define the best response function  $B_i(s_{-i}) = \arg \max_{s_i \in S_i} u_i(s_i, s_{-i})$ . Then
  - $B_i(s_{-i})$  has greatest and least element  $\bar{B}_i(s_{-i})$  and  $\underline{B}_i(s_{-i})$
  - $\bar{B}_i(s_{-i})$  and  $\underline{B}_i(s_{-i})$  are increasing in  $s_{-i}$



# Example: Bertrand game

- ❑ Two firms: firm 1 and firm 2 with prices  $p_1, p_2 \in [0,1]$
- ❑ Payoff  $u_i(p_i, p_j) = p_i(1 - 2p_i + p_j)$
- ❑ It is a supermodular game, since  $\frac{\partial^2 u_i}{\partial p_i \partial p_j} > 0$ .
- ❑ Solve by iterated strict dominance
  - ❑ Let  $S_i^0 = [0,1]$ , then  $S_i^1 = [1/4, 1/2]$ .
    - If  $p_i < 1/4$ , then  $\frac{\partial u_i}{\partial p_i} > 1 - 4 \cdot \frac{1}{4} + p_j \geq 0 \Rightarrow p_i < \frac{1}{4}$  is strictly dominated.
    - If  $p_i > 1/2$ , then  $\frac{\partial u_i}{\partial p_i} < 1 - 4 \cdot \frac{1}{2} + p_j \leq 0 \Rightarrow p_i > \frac{1}{2}$  is strictly dominated.
  - ❑ Let  $S_i^k = [\underline{s}^k, \bar{s}^k]$ , then
 
$$\underline{s}^k = 1/4 + \underline{s}^{k-1}/4 = 1/4 + 1/16 + \underline{s}^{k-2}/16 = \dots = 1/4 + \dots + 1/4^k + \underline{s}^0/4^k$$

$$\bar{s}^k = 1/4 + \bar{s}^{k-1}/4 = 1/4 + 1/16 + \bar{s}^{k-2}/16 = \dots = 1/4 + \dots + 1/4^k + \bar{s}^0/4^k$$
  - ❑  $(1/3, 1/3)$  is the only Nash equilibrium.

- Theorem: let  $G = \{N, S_{i \in N}, u_{i \in N}\}$  be a supermodular game. Then the set of strategies surviving iterated strict dominance (ISD) has greatest and least element  $\bar{s}$  and  $\underline{s}$ , which are pure strategy Nash equilibria.
- Corollary:
  - Pure Nash equilibrium exists.
  - The largest and smallest strategies compatible with ISD, rationalizability, correlated equilibrium and Nash equilibrium are the same.
  - If a supermodular game has a unique Nash Equilibrium, it is dominance solvable.

□ Proof: let  $s^0 = s$  and  $s^0 = (s_1^0, \dots, s_{|N|}^0)$  be the largest element of  $S$ . Let  $s_i^1 = \bar{B}_i(s_{-i}^0)$  and  $S_i^1 = \{s_i \in S_i^0 : s_i \leq s_i^1\}$ . If  $s_i \notin S_i^1$ , i.e.,  $s_i > s_i^1$ , then it is dominated by  $s_i^1$ .

□ By increasing differences

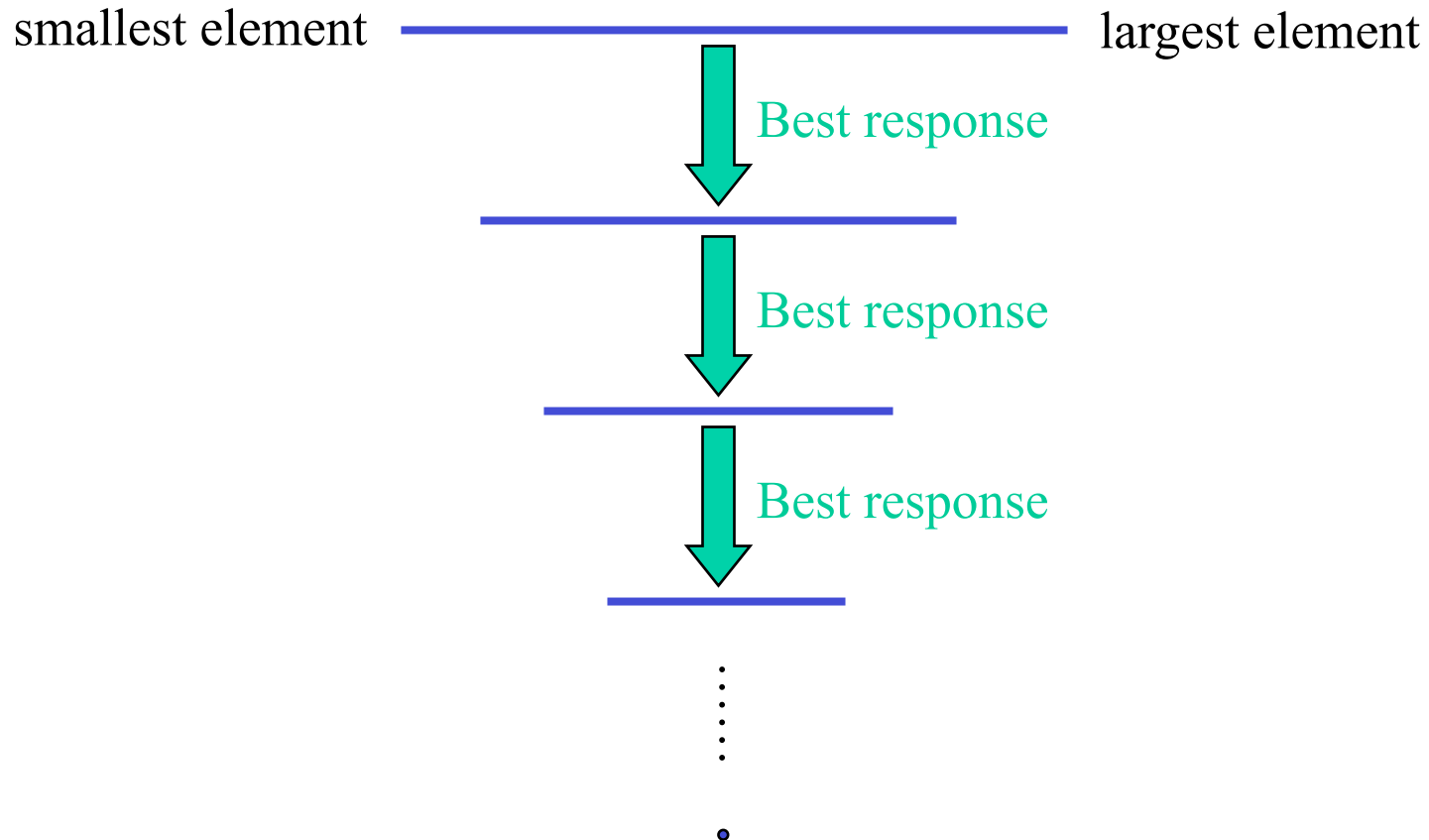
$$u_i(s_i, s_{-i}) - u_i(s_i^1, s_{-i}) \leq u_i(s_i, s_{-i}^0) - u_i(s_i^1, s_{-i}^0) < 0$$

□ Also note that  $s^1 \leq s^0$

□ Iterate and define  $s_i^k = \bar{B}_i(s_{-i}^{k-1})$  and  $S_i^k = \{s_i \in S_i^{k-1} : s_i \leq s_i^k\}$ . Now if  $s^k \leq s^{k-1}$ , then  $s_i^{k+1} = \bar{B}_i(s_{-i}^k) \leq \bar{B}_i(s_{-i}^{k-1}) = s_i^k$ . So,  $\{s^k\}$  is a decreasing sequence and has a limit denoted by  $\bar{s}$ . Only the strategies  $s_i \leq \bar{s}_i$  are undominated.

- Similarly, start with  $s^0 = (s_1^0, \dots, s_{|N|}^0)$  the smallest element of  $S$  and identify  $\underline{s}$ .
- Show  $\bar{s}$  and  $\underline{s}$  are Nash equilibria.
  - For all  $i$  and  $s_i$ ,  $u_i(s_i^{k+1}, s_{-i}^k) \geq u_i(s_i, s_{-i}^k)$
  - Take the limit as  $k \rightarrow \infty$ ,  $u_i(\bar{s}_i, \bar{s}_{-i}) \geq u_i(s_i, \bar{s}_{-i})$ .
  - Similarly, prove  $\underline{s}$  is a Nash equilibrium

# Illustrative diagram



# Submodular games

- Def: suppose  $X \subseteq R$  and  $T$  some partially ordered set. A function  $f : X \times T \rightarrow R$  has **decreasing differences** (submodular) in  $(x, t)$  if for all  $x' \geq x$  and  $t' \geq t$ ,

$$f(x', t') - f(x, t') \leq f(x', t) - f(x, t).$$

- A game is a submodular game if the payoff functions are submodular.
- More generalizations

# Monotonicity

□ Def: let  $A$  and  $B$  are two sets. We say  $A \prec B$  if for any  $a \in A$  and  $b \in B$ ,  $\min(a, b) \in A$  and  $\max(a, b) \in B$ .

□ Component-wise operations

□ For constraint sets  $S_i(s_{-i}) \subseteq S_i$ , if

$$s_{-i} \leq s'_{-i} \Rightarrow S_i(s'_{-i}) \prec S_i(s_{-i}),$$

then the set  $S_i$  possess the descending property.  
The ascending property can be defined when the relation is reversed.

□ Theorem: for a submodular game with descending  $s_i(\cdot)$ ,

□ An Nash equilibrium exists.

□ The best response strategy

$$B_i(s_{-i}) = \min\{\arg \min_{s_i \in S_i(s_{-i})} u_i(s_i, s_{-i})\}$$

monotonically converges to an equilibrium.

□ Proof: Follows monotonicity of the best response. Similar to the proof of former theorem.

□ Similar result exists for a supermodular game with ascending  $s_i(\cdot)$ .



# Power control

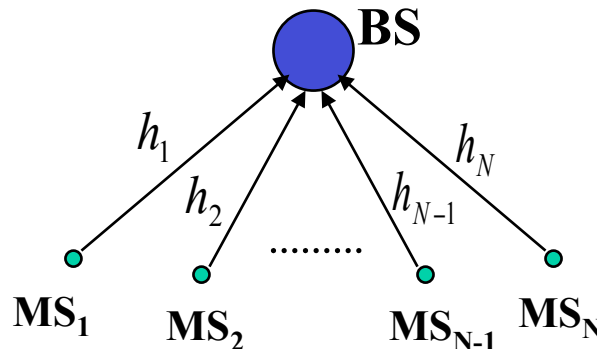
- ❑ An important component of radio resource management
  - ❑ Meet target BER or SIR while limiting interference
  - ❑ Increase capacity by minimizing interference
  - ❑ Extend battery life
- ❑ Users assigned utilities that are functions of the power they consume and the signal-to-interference ratio (SIR) they attain
- ❑ Try to find a good balance between high SIR (or meeting target SIR) and low power consumption

# Power control via pricing

- Consider a single-cell network with a set  $N$  of users at uplink
- Each user  $i$  can choose a power  $p_i \in [p_i^{\min}, p_i^{\max}]$
- The SIR for user  $i$

$$\gamma_i = \frac{h_i p_i}{\sum_{j \neq i} h_j p_j + \sigma^2}$$

where  $h_i$  is the channel gain from MS to BS and  $\sigma^2$  is the noise variance.



- Consider payoff  $u_i(p_i, p_{-i}) = f(\gamma_i) - \alpha_i p_i$
- $f(\cdot)$  assumed to be increasing
- When the utilities are supermodular?

$$\frac{\partial u_i(p_i, p_{-i})}{\partial p_i} = f'(\gamma_i) \frac{\gamma_i}{p_i} - c$$

$$\frac{\partial^2 u_i(p_i, p_{-i})}{\partial p_i \partial p_j} = -\frac{\gamma_i^2 h_j}{h_i p_i^2} (\gamma_i f''(\gamma_i) + f'(\gamma_i)), \quad j \neq i$$

- Requires  $\gamma_i f''(\gamma_i) + f'(\gamma_i) < 0$ 
  - Example: some concave functions

## □ Power control algorithm

□ At time  $t = 0$  , let  $p(0) = p^{\min}$

□ At each time  $t = k$  , set user  $i$  power

$$p_i(k) = \min \{ \arg \max_{p_i} u_i(p_i, p_{-i}(k-1)) \}$$

□ The above algorithm converges to a Nash equilibrium that is the smallest equilibrium.

# A general framework for distributed power control

- Consider a set  $N$  of users and a set of  $M$  base stations
- User  $j$  uses power  $p_j$
- Denote by  $h_{kj}$  the gain of user  $j$  at base station  $k$
- The SIR of user  $j$  at base station  $k$  is  $p_j \mu_{kj}$  with

$$\mu_{kj} = \frac{h_{kj}}{\sum_{i \neq j} p_i h_{ki} + \sigma_k^2}$$

# Different power control schemes

- Fixed assignment: the user  $j$  is assigned to BS  $a_j$  with a SIR requirement  $\gamma_j$ . The constraints is

$$p_j \geq I^{FA}(p) = \frac{\gamma_j}{\mu_{a_j j}(p)}$$

- Minimum power assignment, limited diversity and multiple reception are have the constraints of the same form

$$p_j \geq I(p)$$

# Standard interference function

- The standard interference function  $I(p)$  satisfies the following properties
  - Positivity:  $I(p) > 0$
  - Monotonicity: if  $p \geq p' \Rightarrow I(p) \geq I(p')$
  - Scalability: for  $a > 1$ ,  $aI(p) \geq I(ap)$

- Define a submodular game

- Payoff  $u_j(p) = p_j$

- Constraint set  $S_j(p_{-j}) = \{p_j : p_j \geq I_j(p), 0 \leq p_j \leq p'_j\}$   
with  $p'$  a feasible solution to  $p \geq I(p)$

- Theorem: if a feasible solution  $p'$  exists, then

- There is a fixed point to equation  $p = I(p)$

- The best response strategy converges to an equilibrium.