Financial Econometrics

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Lecture 13

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- The assumption of constant variance implied by stationarity may be inadequate.
- ► Consider a vector $\begin{pmatrix} Y_t & X_{t1} & \cdots & X_{tp} \end{pmatrix}^T \in \mathbb{R}^{p+1}$, $p \in \mathbb{N}$ and suppose,

$$Y_t = m(X_{t1}, \cdots, X_{tp}) + \varepsilon_t$$
 for $t = 1, 2, \cdots$,

and note that

$$\begin{split} E(Y_t|X_{t1},\cdots,X_{tp}) &= m(X_{t1},\cdots,X_{tp}) + E(\varepsilon_t|X_{t1},\cdots,X_{tp}). \\ \text{If } E(\varepsilon_t|X_{t1},\cdots,X_{tp}) &= 0, \text{ then} \\ E(Y_t|X_{t1},\cdots,X_{tp}) &= m(X_{t1},\cdots,X_{tp}) \\ \text{is a regression. Also, if } \sigma^2 &= V(\varepsilon_t|X_{t1},\cdots,X_{tp}), \text{ we have} \end{split}$$

$$V(Y_t|X_{t1},\cdots,X_{tp})=V(\varepsilon_t|X_{t1},\cdots,X_{tp})=\sigma^2.$$

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- The last equation is called a "skedastic function."
- A more general formulation is to write,

$$Y_t = m(X_{t1}, \cdots, X_{tp}) + h^{1/2}(X_{t1}, \cdots, X_{tp})\varepsilon_t$$
 for $t = 1, 2, \cdots$,

for $h : \mathbb{R}^{p} \to \mathbb{R}$ and h > 0. Then,

$$E(Y_t|X_{t1},\cdots,X_{tp})=m(X_{t1},\cdots,X_{tp})$$

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and

$$V(Y_t|X_{t1},\cdots,X_{tp}) = h(X_{t1},\cdots,X_{tp})$$
if $V(\varepsilon_t|X_{t1},\cdots,X_{tp}) = 1$.

This is called a conditional location-scale model.

A special case of this model is the Autoregressive Conditional Heteroskedastic (ARCH) model

- Suppose $\{\varepsilon_t\}_{t\in\mathbb{N}}$ is an IID sequence such that $\varepsilon_t \sim N(0,1)$, and note that $E(\varepsilon_t | \varepsilon_{t-1}, \varepsilon_{t-2}, \cdots) = 0$ and $V(\varepsilon_t | \varepsilon_{t-1}, \varepsilon_{t-2}, \cdots) = 1$.
- A process ${X_t}_{t \in \mathbb{N}}$ is said to follow an ARCH(1) model if,

$$X_t = (lpha_0 + lpha_1 X_{t-1}^2)^{1/2} arepsilon_t$$
 for $t = 1, 2, \cdots$,

In the notation of the previous slide, $h(x) = \alpha_0 + \alpha_1 x^2 > 0$.

It must be that a₀ + a₁x² > 0. Since, h⁽¹⁾(x) = 2a₁x and h⁽²⁾(x) = 2a₁, it must be that a₁ > 0. Also, h reaches a minimum at x = 0 and h(0) = a₀ > 0.

- If X_{t-1} is close to its expectation (0) then h_t ∼ α₀. If not, then h_t = α₀ + α₁X²_{t-1}.
- If the process is covariance stationary

$$E(E(X_t^2|X_{t-1})) = E(X_t^2) = \alpha_0 + \alpha_1 E(X_{t-1}^2),$$

and $E(X_t^2) = \alpha_0/(1 - \alpha_1)$. This exists if $0 < \alpha_1 < 1$.

► Note that for any process {X_t} such that E(X_t|X_{t-1}, X_{t-2},...) = µ we have

$$\begin{aligned} \gamma(1) &= Cov(X_t, X_{t-1}) = E(X_t X_{t-1}) - \mu^2 \\ &= E(E(X_t X_{t-1} | X_{t-1}, \cdots)) - \mu^2 \\ &= E(X_{t-1} E(X_t | X_{t-1}, \cdots)) - \mu^2 = \mu E(X_{t-1}) - \mu^2 = 0 \end{aligned}$$

- In fact, γ(h) = 0 for all h ≠ 0. Hence, ARCH processes are uncorrelated.
- ARCH(1) process is uncorrelated but not independent.
- Contrary to the AR(1) process, that has constant (conditional) variance and changing conditional expectation, ARCH(1) has constant conditional expectation and changing (conditional) variance.

There is no difficulty in introducing a constant in the ARCH model.

• Let $\mu \in \mathbb{R}$, then

$$X_t = \mu + (\alpha_0 + \alpha_1 (X_{t-1} - \mu)^2)^{1/2} \varepsilon_t$$
 for $t = 1, 2, \cdots, ...$

Then, by the LIE, $E(X_t) = \mu$.

Also,

$$E((X_t - \mu)^2 | X_{t-1}) = V(X_t | X_{t-1}) = \alpha_0 + \alpha_1 (X_{t-1} - \mu)^2$$

and

$$V(X_t) = \alpha_0 + \alpha_1 V(X_{t-1})$$

where $V(X_t) = \alpha_0 / (1 - \alpha_1)$.

Example: Combining AR(1) and ARCH(1) Models

• Let $\{X_t\}$ be an ARCH(1) with $\mu = 0$ process and write

$$Y_t - \mu_Y = \phi(Y_{t-1} - \mu_Y) + X_t$$
 for $t = 1, 2, \cdots$,

or

$$Y_t - \mu_Y = \phi(Y_{t-1} - \mu_Y) + (\alpha_0 + \alpha_1 X_{t-1}^2)^{1/2} \varepsilon_t$$
 for $t = 1, 2, \cdots$,

- Since the ARCH process is uncorrelated Y_t has the autocovariance function of an AR(1) process.
- $E(Y_t|Y_{t-1}) = \mu + \phi Y_{t-1}$ if X_t is independent of Y_t
- ► $V(Y_t|Y_{t-1}) = \alpha_0 + \alpha_1 X_{t-1}^2$ if X_t is independent of Y_t

ARCH(q) Models

• We say that $\{X_t\}$ follows an ARCH(q) with $\mu = 0$ process if

$$X_{t} = (\alpha_{0} + \alpha_{1} X_{t-1}^{2} + \alpha_{2} X_{t-2}^{2} + \dots + \alpha_{q} X_{t-q}^{2})^{1/2} \varepsilon_{t} \text{ for } t = 1, 2, \dots,$$

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For estimation see MATLAB code garch_11_gau.m